



1 **Estimating hydraulic conductivity of a crusted loamy soil from beerkan experiments in a**
2 **Mediterranean vineyard**

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13
14 **Abstract**

15 In bare soils of semi-arid areas, surface crusting is a rather common phenomenon due to the impact of
16 raindrops. Water infiltration measurements under ponding conditions constitute a common way for an
17 approximate characterization of crusted soils. In this study, the impact of crusting on soil hydraulic
18 conductivity was assessed in a Mediterranean vineyard (western Sicily, Italy) under conventional tillage. The
19 BEST (Beerkan Estimation of Soil Transfer parameters) algorithm was applied to the infiltration data to
20 obtain the hydraulic conductivity of crusted and uncrusted soils. Soil hydraulic conductivity was found to
21 vary during the year and also spatially (i.e., rows vs. inter-rows) due to crusting, tillage and vegetation cover.
22 A 55 mm rainfall event resulted in a decrease of the saturated soil hydraulic conductivity, K_s , by a factor
23 close to two in the inter-row areas, due to the formation of a crusted layer at the surface. The same rainfall
24 event did not determine a K_s reduction in the row areas (i.e., K_s reduced by a non-significant factor of 1.05)
25 because the vegetation cover intercepted the raindrops and therefore prevented alteration of the soil surface.
26 The developed ring insertion methodology on crusted soil, implying pre-moistening through the periphery of
27 the sampled surface, together with the very small insertion depth of the ring (0.01 m) prevented visible
28 fractures. Consequently, beerkan tests carried out along and between the vine-rows and data analysis by the
29 BEST algorithm allowed to assess crusting-dependent reductions in hydraulic conductivity with
30 extemporaneous measurements alone. Testing the beerkan infiltration run in other crusted soils and



31 establishing comparisons with other experimental methodologies appear advisable to increase confidence on
32 the reliability of the method, that seems suitable to allow simple characterization of crusted soils.

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34

35 **Keywords:** Hydraulic conductivity, water infiltration measurements, soil surface crust, vineyard, BEST
36 procedure

37

38 **1. Introduction**

39 The impact of raindrops on a bare soil surface can result in physical and chemical changes of the exposed
40 soils. The mechanical alteration of the upper soil aggregates, expressed in terms of compaction, splash and
41 particle detachment, contribute to form a surface crust (Assouline, 2004). This type of crust, named structural
42 crusts, differ from depositional crusts (West et al., 1992), which are formed by deposition of detached, fine
43 particles carried out in suspension by runoff (Fox and Le Bissonnais, 1998). The hydraulic properties of
44 crusts vary significantly (Fox et al., 1998a, 1998b). Different physical rainfall properties may be related with
45 structural crust development, such as intensity (Baumhardt et al., 1990; Freebairn et al., 1991; Morin and
46 Benyamini, 1977), kinetic energy (Eigel and Moore, 1983; Mohammed and Kohl, 1987) and momentum
47 (Brodie and Rosewell, 2007; Rose, 1960). The initial or wetting phase in crust formation is defined as
48 surface sealing (Römken, 1979). During the drying cycle, this layer consolidates and may differ from the
49 wetting phase in its mechanical and hydraulic properties (Mualem et al., 1990). This drying phase is known
50 as crusting (Römken, 1979).

51 The hydrodynamic properties of such a layered system (crust layer, underlying soil) may severely affect
52 the partition between infiltration and runoff at the soil surface, especially in arid and semi-arid areas where
53 crusting is a common phenomenon (Angulo-Jaramillo et al., 2016). Water infiltration measurements
54 constitute a common way for an indirect characterization of sealed/crusted soils (Alagna et al., 2013;
55 Bedaiwy, 2008). The Beerkan Estimation of Soil Transfer (BEST) parameters procedure developed by
56 Lassabatere et al. (2006) is a very attractive method for practical use since it allows an estimation of both the
57 soil water retention and hydraulic conductivity functions. The BEST method focuses specifically on the van
58 Genuchten (1980) relationship for the water retention curve with the Burdine (1953) condition and the



59 Brooks and Corey (1964) relationship for hydraulic conductivity. BEST estimates shape parameters, which
60 are texture dependent, from particle-size analysis by physical-empirical pedotransfer functions, and scale
61 parameters from beerkan experiments (Haverkamp et al., 1996), i.e. three-dimensional (3D) field infiltration
62 experiments at ideally zero pressure head. BEST substantially facilitates the hydraulic characterization of
63 unsaturated soils, and it is gaining popularity in soil science (Bagarello et al., 2014a; Castellini et al., 2016;
64 Di Prima, 2015; Di Prima et al., 2016b; Gonzalez-Sosa et al., 2010; Mubarak et al., 2010). Alternative
65 algorithms, i.e., BEST-slope (Lassabatere et al., 2006), BEST-intercept (Yilmaz et al., 2010) and BEST-
66 steady (Bagarello et al., 2014b), and field procedures based on BEST method were developed (Alagna et al.,
67 2016; Bagarello et al., 2014c; Di Prima et al., 2016a). The ability of the BEST method to distinguish between
68 crusted and non-crusted soils was demonstrated by Souza et al. (2014). Moreover, Di Prima et al. (2016a)
69 successfully applied a beerkan experiment involving different heights of water pouring on the infiltration
70 surface to explain surface runoff and sealing generation phenomena occurring during intense rainfall events.
71 These authors concluded that if any seal forms at the surface, the beerkan infiltration test should detect its
72 impact on flow and BEST estimates should essentially indicate the hydraulic properties of the surface layer.
73 In fact, the BEST method was developed for non-layered soils that are assumed to be uniform and have a
74 uniform soil water content at the beginning of the infiltration run (Lassabatere et al., 2006, 2009) and should
75 not contain a macropore network (Lassabatere et al., 2014). However, completely homogeneous soils are
76 very rare in natural environments (Reynolds and Elrick, 2002). Therefore, the hydraulic conductivity
77 obtained by an infiltrometer method, such as BEST, should probably be considered as an equivalent
78 conductivity, i.e. the conductivity of a rigid, homogeneous and isotropic porous medium characterized by
79 infiltration rates that are the same as those actually measured on the real soil (Bagarello et al., 2010). For the
80 case of stratified media, the layer with the lowest hydraulic conductivity generally controls the flow and
81 consequently cumulative infiltration at the surface (Alagna et al., 2013). Therefore, water infiltration data
82 can be regarded as representative of the hydraulic behavior of the least permeable layer, and therefore the
83 derived BEST parameters can be assigned to this layer. This approach was proposed by Lassabatere et al.
84 (2010) for a stratified medium with a low permeability sedimentary layer at the surface, by Yilmaz et al.
85 (2010, 2013), for the characterization of crusted reactive materials, and, recently, by Coutinho et al. (2016)
86 for a permeable pavement for stormwater management in an urban area.



87 In this paper we tested the BEST method in an agricultural setting with general objective to carry out a
88 hydraulic characterization of a loamy soil in a vineyard under conventional tillage located at Marsala
89 (western Sicily, Italy). In particular, both row and inter-row areas were sampled since a crust layer only
90 developed in the latter area. Therefore, the specific objective was to check the ability of the BEST method to
91 yield plausible estimates of saturated hydraulic conductivity of crusted and non-crusted soils.

92

93 **2. Material and methods**

94 **2.1. Study site**

95 The experimental site is located close to Marsala (western Sicily, Italy), in the homeland of Sicilian
96 viticulture (37°48'5.10" N and 12°30'44.79" E). Elevation is 111 m a.s.l. and soil surface is flat. The soil is a
97 typic Rhodoxeralf with a depth of 1 m and a small amount of gravel. According to the USDA classification,
98 the soil texture, determined on two replicated soil samples, is loam (**Table 1**). A weather station is located 5
99 km away from the sampling site (37°79'35.64"N and 12°56'81.59"E). It is positioned at the same elevation as
100 the sampling site and it is part of a network of stations managed by Servizio Informativo Agrometeorologico
101 Siciliano –SIAS.

102 At the sampling site, the common soil management for the vineyards of Marsala was applied during the
103 two years of sampling (2015 and 2016) (**Figure 1**). The soil is tilled to a depth of 0.10-0.15 m in October,
104 after the first autumn rainfalls. Faba bean (*Vicia faba* L. var. *minor*) is sown in November between the rows.
105 In March, the legume biomass is cut and immediately incorporated into the soil with a rotary tiller to a depth
106 of 0.20 m. Finally, a new rotary tillage is performed in May and, only for the second year, this was also done
107 in June. This soil management practice is applied between the rows. Along the rows, a mechanical topper is
108 used at each soil tillage date to a depth of 0.10 m.

109

110 **2.2. Soil sampling**

111 An area of approximately 100 m² was sampled on three different sampling campaigns covering two
112 growing seasons. The first two campaigns were carried out at the beginning and the end of September 2015,
113 respectively, and the third campaign was performed at the beginning of July 2016. Between the first two
114 sampling campaigns, the soil was not tilled and a total rainfall of 55 mm fell (**Figure 1**), which is



115 approximately 10% of the average annual precipitation for the area. In particular, a 29-mm event occurred
116 during the morning of 9 September, with a maximum recorded intensity of 25 mm h^{-1} . During the same day,
117 a total of 44.6 mm of precipitation was recorded. This rainfall led to the development of a weak but clearly
118 detectable surface crust (thickness of $\sim 4 \text{ mm}$) (**Figure 2**). This phenomenon was only observed between the
119 rows and not along the rows. The second sampling was done one week after the last rainfall event. Finally, a
120 third sampling campaign was carried out during the following dry season in order to sample the soil after the
121 ordinary tillage practices and with moisture conditions comparable to the first sampling date.

122 On each sampling date, a total of 10 undisturbed soil cores (5 cm in height by 5 cm in diameter) were
123 collected at the soil surface close to the points where the infiltration tests were performed, 5 along the rows
124 and 5 between the rows. These cores were used to determine the dry soil bulk density, ρ_b (g cm^{-3}), and the
125 soil water content at the time of the experiment, θ , ($\text{cm}^3 \text{ cm}^{-3}$). The soil porosity was calculated from the ρ_b
126 data, assuming a soil particle density of 2.65 g cm^{-3} . A disturbed soil sample (0–10-cm depth), collected both
127 along and between the rows, was used to determine the particle size distribution (PSD), using conventional
128 methods (Gee and Bauder, 1986). Fine size fractions were determined by the hydrometer method, whereas
129 the coarse fractions were obtained by mechanical dry sieving. The clay, silt and sand percentages were
130 determined from the measured PSD according to the USDA standards.

131

132 **2.3. Beerkan experiments**

133 For each sampling date, an area of approximately 100 m^2 was chosen and 14 beerkan infiltration runs
134 (Lassabatere et al., 2006) were carried out using a 15 cm inner-diameter ring. Seven runs were carried out
135 along the rows and seven on the bare inter-rows area (**Figure 3**). The steel ring was positioned between two
136 vine stocks along the row and in the same orthogonal direction between the rows. The ring was inserted to a
137 depth of about 0.01 m into the soil surface to avoid lateral loss of the ponded water. On crusted soil, to
138 prevent fracture of the upper layer during ring insertion, the soil outside the hedge of the ring was moistened
139 with 5 cm^3 of water by means of a syringe before insertion. After ten minutes, the ring was carefully inserted
140 to the pre-established short depth applying a slight pressure and a gentle rotation. This site preparation was
141 essential to prevent crust surface perturbation.



142 According to the guidelines by Lassabatère et al. (2006), for each run a known volume of water (150 mL)
143 was poured in the cylinder at the start of the experiment and the elapsed time during its infiltration was
144 measured. When the amount of water had completely infiltrated, another identical volume of water was
145 poured on the confined infiltration surface and the time needed for the complete infiltration was logged. The
146 procedure was repeated 15 times for each run by applying water at a small distance (3 cm of height) from the
147 infiltration surface. As is commonly suggested in practical application of a ponding infiltration method, the
148 energy of the water due to the application was dissipated on the fingers of a hand in order to minimize soil
149 disturbance (Reynolds, 2008).

150 Di Prima et al. (2016b) showed that all BEST algorithms, i.e. BEST-slope, BEST-intercept and BEST-
151 steady, led to similar results in most cases. However, BEST-slope appeared to yield more accurate estimates,
152 especially of the saturated soil hydraulic conductivity, K_s (mm h^{-1}), but it was affected by a failure rate
153 higher than others algorithms (Bagarello et al., 2014b). In this study, such a problem did not occur and,
154 therefore, the BEST-slope algorithm (Lassabatere et al., 2006) was considered to estimate the whole set of
155 parameters of the hydraulic conductivity function. BEST focuses specifically on the Brook and Corey (1964)
156 relationship:

$$157 \quad \frac{K(\theta)}{K_s} = \left(\frac{\theta - \theta_r}{\theta_s - \theta_r} \right)^\eta \quad (1)$$

158 where K (L T^{-1}) is the soil hydraulic conductivity, θ ($\text{cm}^3\text{cm}^{-3}$) is the volumetric soil water content, θ_r
159 ($\text{cm}^3\text{cm}^{-3}$) is the residual volumetric soil water content, θ_s ($\text{cm}^3\text{cm}^{-3}$) is the saturated volumetric soil water
160 content, and η is a shape parameter linked to the soil textural properties. In BEST, η is estimated from the
161 analysis of the PSD with the pedotransfer function included in the procedure, whereas θ_s , θ_r and K_s are scale
162 parameters. BEST considers θ_r to be zero, and θ_s was assumed to coincide with soil porosity in this
163 investigation, as suggested by many authors (Bagarello et al., 2011; Di Prima, 2015; Di Prima et al., 2016a;
164 Mubarak et al., 2010; Xu et al., 2009). In particular, Di Prima et al. (2016a) demonstrated that the assumed
165 coincidence between saturated soil water content and porosity did not practically affect the K_s estimation.

166 BEST-slope estimates sorptivity, S ($\text{mm h}^{-0.5}$), by fitting the experimental cumulative infiltration data on
167 the explicit transient two-term equation by Haverkamp et al. (1994):



$$I(t) = S\sqrt{t} + [A(1-B)S^2 + B i_s] t \quad (2)$$

where I (mm) is 3D cumulative infiltration and t (h) is the time. Then, K_s (mm h^{-1}) is estimated as a function of S as follow:

$$K_s = i_s - AS^2 \quad (3)$$

where i_s (mm h^{-1}) is the experimental steady-state infiltration rate, which is estimated by linear regression analysis of the last data points describing steady-state conditions on the I vs. t plot and corresponds to the slope of the regression line. The constants A (mm^{-1}) and B can be defined for the specific case of a Brooks and Corey relation (Eq. 1) and taking into account initial soil water content, θ_i ($\text{cm}^3\text{cm}^{-3}$), as (Haverkamp et al., 1994):

$$A = \frac{\gamma}{r(\theta_s - \theta_i)} \quad (4a)$$

$$B = \frac{2-\beta}{3} \left[1 - \left(\frac{\theta_i}{\theta_s} \right)^\eta \right] + \left(\frac{\theta_i}{\theta_s} \right)^\eta \quad (4b)$$

where γ (parameter for geometrical correction of the infiltration front shape) and β are coefficients that are commonly set at 0.75 and 0.6 for $\theta_i < 0.25 \theta_s$, and r (mm) is the radius of the source.

181

182 2.4. Data analysis

183 Data sets were summarized by calculating the mean, M , and the associated coefficient of variation, CV . In
184 particular, the cl , si , sa , ρ_b , θ_s values were considered site specific and therefore they were determined only in
185 duplicate (cl , si , sa , $N = 2$) or, considering their low variability (ρ_b , θ_s), the arithmetic mean and the
186 associated CV were calculated (**Table 1**). Temporal variability of θ_i was determined on the basis of ten
187 replicate samples on each sampling date (**Table 2**). The K_s data were assumed to be log-normally distributed
188 since the statistical distribution of these data is generally log-normal (Lee et al., 1985; Warrick, 1998). The
189 geometric mean and the associated CV were therefore calculated to summarize K_s values using the
190 appropriate “log-normal equations” (Lee et al., 1985). Statistical comparison between two sets of data was
191 conducted using two-tailed t-tests, whereas the Tukey Honestly Significant Difference test was applied to
192 compare three sets of data. The ln-transformed K_s data were used in the statistical comparison. A probability
193 level, $P = 0.05$, was used for all statistical analyses.



194

195 **3. Results and discussion**

196 In this paper, the BEST method was applied in an agricultural setting. In particular, the hydraulic
197 properties of a loamy soil were determined in a vineyard under conventional tillage located at Marsala
198 (western Sicily, Italy). The investigation was specifically aimed at checking the ability of the BEST method
199 to yield plausible estimates of saturated hydraulic conductivity of crusted and non-crusted soils, since a
200 limited experimental information is still available in the scientific literature (Souza et al., 2014).
201 Consequently, both row and inter-row areas were sampled since a crust layer developed only in the latter
202 portion of the field site. The 42 infiltrations runs were analyzed with the BEST-slope algorithm, yielding
203 positive K_s values in all cases. In addition, the fitting of the infiltration model to the transient phase of the
204 infiltration run always yielded relative errors lower than 5.5% (Lassabatere et al., 2006), denoting an
205 acceptable error for transient cumulative infiltration (**Figure 4**).

206

207 **3.1. Impact of surface crusting on hydraulic conductivity in vineyards**

208 During the second field campaign, the crust layer only affected water infiltration between the rows (**Table**
209 **3**), suggesting that the protective role of vegetation along the rows was effective. The cover intercepted
210 raindrop energy preventing surface sealing (Dunne et al., 1991). The protective role along the vine-rows is
211 well known, while in vine inter-rows the mulching practice is commonly applied to protect soil from
212 raindrop impact (Celette et al., 2008; Prosdocimi et al., 2016). For the second campaign, the mean K_s value
213 obtained between the rows was 1.6 times lower than the one obtained along the rows (**Figure 5**). In
214 particular, this latter value, equal to 212.4 mm h^{-1} , did not significantly differ from those of the first and third
215 sampling dates (**Table 3**). On the other hand, during these last two campaigns, beerkan runs carried out along
216 and between the rows also yielded similar K_s values, due to the absence of a crust between the rows. This
217 experimental information suggested that the crusting occurrence, the adopted soil management and the cover
218 influenced both the temporal and the spatial variation of the soil hydrological characteristics at the field-
219 scale.

220 Bradford et al. (1987) reported for 20 soils (varying in texture from sand to clay) a reduction in
221 infiltration rate after 60 min of simulated rainfall (intensity of 63 mm h^{-1}), due to the effect of surface sealing



222 on infiltration. Bagarello et al. (2014c), Alagna et al. (2016) and Di Prima et al. (2016a) applied on five soils
223 having different texture a BEST derived procedure to explain surface runoff and disturbance phenomena at
224 the soil surface occurring during intense rainfall events. These authors reported saturated hydraulic
225 conductivity values of the disturbed soil from nine to 33 times lower than the undisturbed soils. In particular,
226 Di Prima et al. (2016a) applied this methodology in a vineyard with a sandy-loam texture. These authors
227 compared this simple methodology with rainfall simulation experiments establishing a physical link between
228 the two methodologies through the kinetic energy of the rainfall and the gravitational potential energy of the
229 water used for the beerkan runs. They also indirectly demonstrated the occurrence of a certain degree of
230 compaction and mechanical breakdown using a mini disk infiltrometer (Decagon, 2014). With this device,
231 they reported a reduction of the unsaturated hydraulic conductivity by 2.3 times due to the seal formation. In
232 another investigation carried out in Brazil with the BEST procedure, non-crusted soils were three times more
233 conductive than the crusted soil (Souza et al., 2014).

234
235

236 **3.2. Seasonal dynamics in hydraulic conductivity**

237 For the first and the third campaign, the beerkan runs carried out between the rows yielded comparable
238 and statistically similar (**Table 3**) K_s values (**Figure 5**). In both cases, the average K_s values were
239 approximately 20 times higher than the expected saturated conductivity on the basis of the soil textural
240 characteristics alone (e.g., $K_s = 10.4 \text{ mm h}^{-1}$ for a loam soil according to Carsel and Parrish, 1988). This
241 circumstance suggested that soil macroporosity generated by soil tillage in the ploughed horizon likely
242 influenced measurement of K_s (Alagna et al., 2016; Di Prima et al., 2016a; Josa et al., 2010). In these
243 conditions, the soil structure is expected to be particularly fragile, especially with reference to macroporosity,
244 and hence unstable (Jarvis et al., 2008), which implies that clogging of the largest pores at the soil surface, as
245 a consequence of the aggregates breakdown occurring during a rainstorm, can easily mitigate tillage effects
246 on soil hydraulic properties (Ciollaro and Lamaddalena, 1998).

247 As discussed in the former section, the presence of the crust layer during the second field campaign
248 clearly affected water infiltration between the rows. In particular, the presence of this layer implied that K_s
249 was 1.5-1.8 times lower than that measured in the absence of the crusted layer (**Figure 5**). Crusting at the



250 soil surface determined an increased hydraulic resistance to water penetration into soil (Alagna et al., 2013)
251 since differences between the K_s datasets (second against first and third sampling campaigns) were
252 statistically significant. Crusting also resulted in a decrease of the lowest measurable K_s values, while the
253 highest values remained unchanged (**Table 3**).

254 The tillage practices carried out in the spring 2016 removed any existing soil crust and thereby increased
255 soil infiltration properties (**Figure 5**) (Chahinian et al., 2006; Ndiaye et al., 2005; Pare et al., 2011; Strudley
256 et al., 2008; Xu and Mermoud, 2001; Zhai et al., 1990), suggesting a cycling occurrence of crusting
257 phenomena within the year.

258 Many studies in the literature have reported similar dynamics, even in vineyards. In fact, infiltration
259 experiments constitute an indirect measurement closely associated with sealing or crusting (Römken et al.,
260 1990), and the saturated hydraulic conductivity may vary considerably during the year if these phenomena
261 occur. In particular, rainfall and wetting–drying cycles favor soil reconsolidation and soil-surface sealing or
262 crusting, whereas tillage removes existing layering (Pare et al., 2011). For instance, Biddoccu et al. (2017)
263 studied temporal variability of soil hydraulic properties in a vineyard on a silt loam soil. These authors
264 reported hydraulic conductivity values measured during the summer four times lower than those measured
265 during the wet season, due to the presence of a structural crust resulting from rainfall events following the
266 late spring tillage.

267

268 **3.3. Applicability of the beerkan runs for the assessment of the crusted soil**

269 The results reported in this investigation were in agreement with those by Souza et al. (2014) and
270 therefore the supported the suggestion that the beerkan-based methodology should be usable to distinguish
271 between crusted and non-crusted soils.

272 Indeed, the hydrodynamic properties of both the crust and the underlying soil play a key role during a
273 rainstorm, affecting the partition between infiltration and runoff (Assouline and Mualem, 2002, 2006).
274 However, transient methods, as the beerkan one, appears appropriate to characterize crusted soils, since the
275 properties of the surface layer play a major role at early stages of the infiltration process (Vandervaere et al.,
276 1997). Recently, Di Prima et al. (2016b) showed that BEST-slope is less sensitive to the attainment of
277 steady-state and allows to obtain accurate estimates of saturated soil hydraulic conductivity with less water



278 and hence shorter experimental times than the other two BEST algorithms. For these reasons, BEST-slope
279 appears suitable, among the alternative algorithms, to characterize a crust layer. The applied methodology in
280 this investigation seems suitable to explore in the future the functional dynamics of the crust layer under
281 natural rainfall conditions.

282 A perplexity on the possibility to collect reliable data on crusted soils by a ponding infiltration experiment
283 is related to the need to insert the ring into the soil. The doubt is that ring insertion could determine fractures
284 in the crusted layer and these fractures could directly connect the ponded depth of water during the run with
285 the underlying, non-crusted, soil layer (Vandervaere et al., 1997). In other terms, ring insertion could
286 impede, in practice, measurement of fluxes through the crusted layer. In this investigation, fractures were not
287 visually detected at the soil surface, perhaps because the soil was not very dry when the experiment on the
288 crusted layer was performed (**Table 2**), the ring insertion depth was small (0.01 m), and insertion was carried
289 out a few minutes after moistening the insertion circumference. Other ponding infiltration techniques, such
290 as the single-ring pressure infiltrometer (Reynolds and Elrick, 1990) or, particularly, the simplified falling
291 head technique (Bagarello et al., 2004), presuppose appreciably deeper insertions of the ring and,
292 consequently, more risk to disrupt or alter the fragile crust layer at the soil surface during ring insertion.
293 Therefore, the beerkan run seems a more appropriate ponding infiltration run to prevent, or minimize,
294 substantial alteration of the surface to be sampled. Obviously, this conclusion needs additional testing but the
295 premises are encouraging, also considering that beerkan runs were successfully conducted in other crusted
296 soils (Souza et al., 2014).

297

298 **4. Conclusions**

299 A loam soil was sampled in a Mediterranean vineyard located at Marsala (western Sicily, Italy), with
300 beerkan infiltration experiments carried out along the rows direction and in the inter-rows within two
301 consecutive growing seasons. Beerkan tests along with BEST-slope algorithm led to accurate estimates in
302 both crusted and un-crusted conditions, allowing to assess the effect of the cycling occurrence of crusting
303 due to rainfalls and wetting–drying cycles on the vineyard inter-rows.

304 A sampling strategy implying beerkan tests carried out along and between the vine-rows was successfully
305 applied. This strategy allowed to assess the reduction in hydraulic conductivity with extemporaneous



306 measurements alone. Its main advantage is that it allows a rapid assessment of crusting severity affecting
307 water infiltration. At the sampled site, the impact of crusting on saturated soil hydraulic conductivity was
308 moderate.

309 In conclusion, the hypothesis that the beerkan runs are suitable enough to detect the effect of the crust on
310 flow and BEST estimates appeared reasonable. In the future, the beerkan-based methodology should be
311 checked in other crusted soils. Comparisons should also be established with other experimental
312 methodologies.

313

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318

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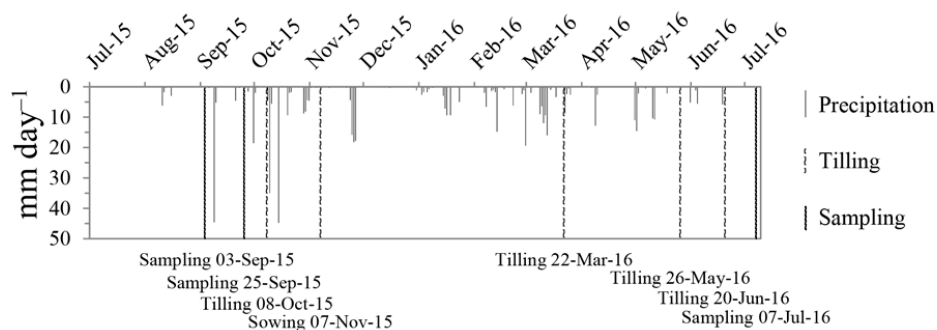


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501 **Figure 1.** Precipitation and soil management program during the study period. The sapling dates are
502 reported.



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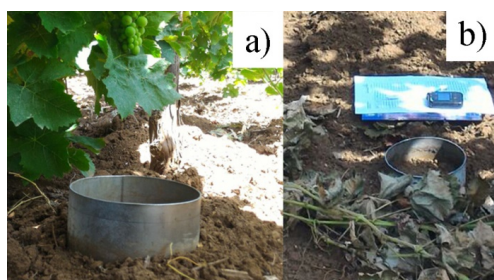
506 **Figure 2.** Surface crust layer developed after the intense storms fallen in September 2015.



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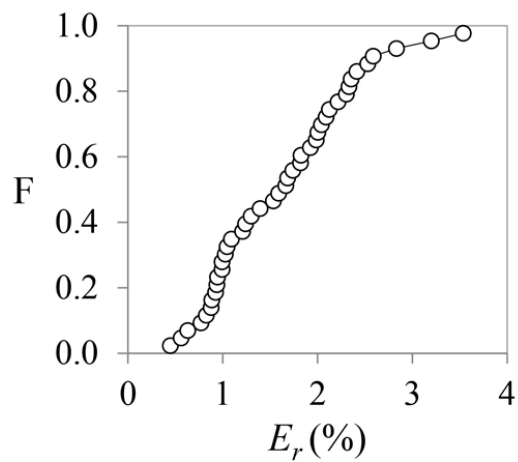
509 **Figure 3.** Beerkan infiltration runs carried out **(a)** along the rows and **(b)** on the bare inter-rows area.



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512 **Figure 4.** Cumulative frequency distribution of the relative errors, E_r (%), of the fitting of the infiltration
513 model to the transient phase of the infiltration runs.

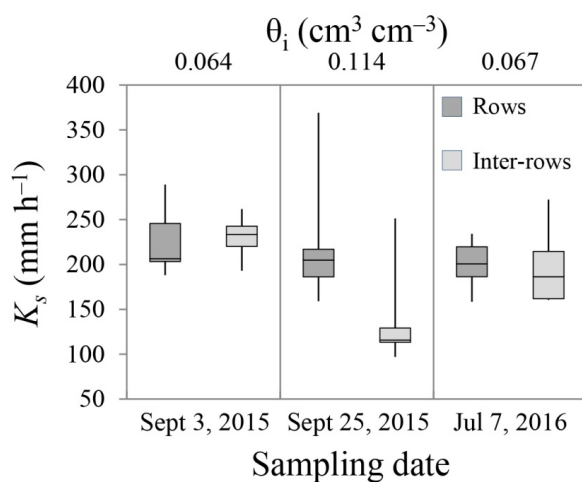


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516 **Figure 5.** Box plots of the saturated soil hydraulic conductivity, K_s (mm h^{-1}), values obtained from BEST
517 experiments carried out along and between the rows on different sampling dates and for different initial soil
518 water content, θ_i ($\text{cm}^3 \text{cm}^{-3}$), values. On the box plots, boundaries indicates median, 25th and 75th quantiles,
519 the top and bottom whiskers indicate the minimum and maximum values.



520

521



522 **Table 1.** Clay (%), silt (%) and sand (%) content (USDA classification system), soil textural classification,
523 dry soil bulk density, ρ_b (g cm^{-3}), and saturated soil water content, θ_s ($\text{cm}^3\text{cm}^{-3}$), of the sampled vineyard
524 soil. Coefficient of variation (%) in brackets.

Variable	Site characteristic
clay	19.7
silt	49.6
sand	30.7
Textural classification	loam
ρ_b	1.128 (5.1)
θ_s	0.575 (3.8)

525

526



527 **Table 2.** Sample size (N), minimum (Min), maximum (Max), mean, and coefficient of variation (CV, in %)
528 of the soil water content at the time of sampling, θ_i ($\text{cm}^3\text{cm}^{-3}$), values for different sampling dates.

Statistic	Sept 3, 2015	Sept 25, 2015	Jul 7, 2016
N	10	10	10
Min	0.051	0.093	0.047
Max	0.073	0.133	0.087
Mean	0.064 A	0.114 B	0.067 A
CV	12.0	10.9	18.1

529
530 The values in a row followed by the same upper case letter were not significantly different according to the
531 Tukey Honestly Significant Difference test ($P = 0.05$). The values followed by a different upper case letter
532 were significantly different.
533



534 **Table 3.** Sample size (N), minimum(Min), maximum (Max),mean, and coefficient of variation (CV, in %) of
 535 the saturated soil hydraulic conductivity, K_s (mm h^{-1}), values obtained from BEST experiments carried out
 536 along and within the rows on different sampling dates.

Variable	Position	Statistic	Sept 3, 2015	Sept 25, 2015	Jul 7, 2016
K_s	Rows	N	7	7	7
		Min	188.1	159.1	158.4
		Max	289.1	369.1	234.2
		Mean	223.6 a A	212.4 a A	199.2 a A
		CV	15.4	27.6	14.1
	Inter-rows	N	7	7	7
		Min	193.0	97.0	160.6
		Max	261.8	251.3	272.3
		Mean	229.5 a A	129.3 b B	192.5 a A
		CV	10.3	31.7	20.2

537
 538 The values in the column followed by a different lower case letter were significantly different according to a
 539 two tailed t test ($P = 0.05$). The values in a row followed by a different upper case letter were significantly
 540 different according to the Tukey Honestly Significant Difference test ($P = 0.05$).