



A probabilistic approach to quantifying soil property change through time integration of energy and mass input

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31 **Abstract**

32 Soils form as the result of a complex suite of biogeochemical and physical processes;
33 however, effective modeling of soil property change and variability is still limited, and does not
34 yield widely applicable results. We suggest that predicting a distribution of probable values
35 based upon the soil-forming state factors is more effective and applicable than predicting discrete
36 values. Here we present a probabilistic approach for quantifying soil property variability through
37 integrating energy and mass inputs over time. We analyzed changes in the distributions of soil
38 texture and solum thickness as a function of increasing time and pedogenic energy (effective
39 energy and mass transfer, EEMT) using soil chronosequence data compiled from literature.
40 Bivariate normal probability distributions of soil properties were parameterized using the
41 chronosequence data; from the bivariate distributions, conditional univariate distributions based
42 on the age and flux of matter and energy into the soil were calculated, and probable ranges of
43 each soil property determined. We tested the ability of this approach to predict the soil properties
44 of the original soil chronosequence database, and soil properties in complex terrain at several
45 Critical Zone Observatories in the U.S. The presented probabilistic framework has the potential
46 to greatly inform our understanding of soil evolution over geologic time-scales. Considering
47 soils probabilistically captures soil variability across multiple scales and explicitly quantifies
48 uncertainty in soil property change with time.

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54 1. Introduction

55 The need for pedogenic models that can be widely applied and easily utilized is
56 paramount for understanding soil-landscape evolution, soil property change with time, and
57 predicting future soil conditions. A mathematically simple, easily parameterized approach has
58 yet to be developed that is capable of predicting current soil properties or recreating potential soil
59 evolution with time. Here we address this knowledge gap through development of a probabilistic
60 model of soil property change capable of predicting soil properties across a wide range of
61 terrains, climates, and ecosystems.

62 The state factor approach has been one of the primary pedogenic models since it's
63 development in the late 1800's and early 1900's (Dokuchaev, 1883; Jenny, 1941). The soil state
64 factor approach (Jenny, 1941) assumes the state of the soil system or specific soil properties (S)
65 may be described as a function of the external environment, represented by climate (cl), biology
66 (o), relief (r), parent material (p), and time (t): $S = f(cl, o, r, p, t)$. This approach increased our
67 understanding of soil variation across each factor, but more complex, multivariate approaches are
68 generally not possible or difficult to derive from this formulation (Yaalon, 1975). From the
69 original state factor model have evolved pedogenic models that include functional approaches
70 (Jenny, 1961), energetic approaches (Rasmussen and Tabor, 2007; Rasmussen et al., 2005, 2011;
71 Runge, 1973; Smeck et al., 1983; Volobuyev, 1964), and mechanistic approaches (Finke, 2012;
72 Minasny and McBratney, 1999; Salvador-Blanes et al., 2007; Vanwallegghem et al., 2013).
73 However, many of these approaches are either limited to a site-specific basis, require a high
74 degree of parameterization, or lack wide-scale applicability.

75 Here we develop a simple probabilistic approach to predict soil physical properties using
76 a large dataset of chronosequences studies. The model compresses state factor variability into 2



key components (parent material and total pedogenic energy, defined in Section 1.1) that were parameterized and calibrated using the chronosequence database. Additionally, we modified the model to include soil depth to capture the influence of redistributive hillslope processes to predict soil properties. We hypothesized that by including soil depth, the model would effectively predict the clay content in an independent dataset synthesizing soil and landscape variability in complex, hilly terrain from a wide range of environments.

1.1 Probabilistic model of soil property change

The model presented here is based on a reformulated state-factor model, where a location has a probability of displaying a range of differing soil morphologies and properties based upon the state factors, with some range of values more probable than others, meaning the state-factor model (Jenny, 1941) may be restated as:

$$\mathbb{P}(s_1 \leq S \leq s_2) = f(\text{cl}, o, r, p, t) \quad (1)$$

where, the left hand side of the equation, $\mathbb{P}(s_1 \leq S \leq s_2)$, represents the probability that a given soil will have a value located between a lower limit (s_1) and an upper limit (s_2) (Phillips, 1993b). Eq. 1 can be restated more simply as:

$$\mathbb{P}(s_1 \leq S \leq s_2) = f(L_o, P_x, t) \quad (2)$$

where, the original soil forming state factors have been simplified to represent the fluxes of matter and energy into the soil system (P_x), incorporating the influence of climate and biology, and the initial state of the soil forming conditions (L_o), incorporating the influence of the initial topography and original soil parent material, and time or age of the soil system (t) (Jenny, 1961).

Equation 2 was further simplified to make the approach operational. A quantitative measure of climate and biology was needed to represent the influence of P_x on soil formation.



We used a quantification of P_x calculated from effective precipitation and biological productivity, termed effective energy and mass transfer (EEMT, $J\ m^{-2}\ yr^{-1}$) (Rasmussen and Tabor, 2007; Rasmussen et al., 2005, 2011). EEMT provides a measure of the energy transferred to the subsurface, in the form of reduced carbon from primary productivity and heat transfer from effective precipitation, which has the potential to perform pedogenic work, e.g., chemical weathering and carbon cycling. Using EEMT as a simplification of P_x , Eq. 2 was restated as (Rasmussen et al., 2011):

$$\mathbb{P}(s_1 \leq S \leq s_2) = f(L_o, EEMT, t) \quad (3)$$

We further simplified Eq. 3 by combining the flux term EEMT and the age of the soil system (t). EEMT multiplied by the age of the soil system, i.e. $EEMT \cdot t$, provides an estimate of the total energy transferred to the soil system over the course of its evolution, referred to here as “total pedogenic energy” (TPE, $J\ m^{-2}$). The TPE provides an estimate of P_x that incorporates soil age, thus Eq. 3 may be restated as:

$$\mathbb{P}(s_1 \leq S \leq s_2) = f(L_o, TPE) \quad (4)$$

where at a certain point in time the probability of a soil property existing between s_1 and s_2 is a function of L_o and TPE. Explicitly including time in Eq. 4 through TPE partially captures variation in soil property change attributable to topography and parent material. Soil residence time may be directly related to landscape position through topographic control on soil production and sediment transport/deposition (Heimsath et al., 1997, 2002; Yoo et al., 2007). Additionally, parent material modulates soil residence time through control on soil depth (Heckman and Rasmussen, 2011; Rasmussen et al., 2005), soil production, and sediment transport rates (Andre and Anderson, 1961; Portenga and Bierman, 2011). The initial conditions of the soil forming system (L_o) are never fully known; however, representing the state of the soil system as a



probable distribution of values, implicitly accounting for soil age, and not constraining the initial soil forming conditions, Eq. 4 can be stated simply as:

$$\mathbb{P}(s_1 \leq S \leq s_2) = f(\text{TPE}) \quad (5)$$

where the probability state of the soil, $\mathbb{P}(s_1 \leq S \leq s_2)$, bounded by a lower and upper limit, is a function of one quantifiable variable.

Quantitatively realizing Eq. 5 required the use of predetermined joint probability density functions parameterized with TPE and a selected soil physical property. Bivariate normal density functions were calculated to determine the probability of a soil property range given a TPE value. The bivariate normal density distribution (Ugarte et al., 2008) was calculated as:

$$f(x, y) = \frac{1}{2\pi\sigma_x\sigma_y\sqrt{1-\rho^2}} \exp\left(-\frac{1}{2(1-\rho^2)}\left[\frac{(x-\mu_x)^2}{\sigma_x^2} + \frac{(y-\mu_y)^2}{\sigma_y^2} - \frac{2\rho(x-\mu_x)(y-\mu_y)}{\sigma_x\sigma_y}\right]\right) \quad (6)$$

where, ρ represents the correlation coefficient, μ_x is the mean of TPE, μ_y is the mean of the selected soil physical property, σ_x is the standard deviation of TPE, σ_y is the standard deviation of the selected soil physical property. Using the bivariate normal density functions, conditional mean and variance values were calculated given a value of TPE; the conditional means and variances parameterized conditional univariate normal distributions for the selected soil physical properties. The conditional mean (Ugarte et al., 2008) was calculated as:

$$\mu_{Y|X=x} = \mu_y + \rho \frac{\sigma_y}{\sigma_x} (x - \mu_x) \quad (7)$$

where, $\mu_{Y|X=x}$ is the conditional mean soil property value given a value for TPE. The conditional variance (Ugarte et al., 2008) was calculated as:

$$\sigma_{Y|X=x}^2 = \sigma_y^2 (1 - \rho^2) \quad (8)$$

where, $\sigma_{Y|X=x}^2$ is the conditional variance of the soil property given a value of TPE.



144 Applying this approach required certain assumptions and simplifications. The model
 145 assumes that climate was constant over the entire duration of pedogenesis. The model makes no
 146 assumptions about the progressive and regressive processes that drive pedogenesis; by weighing
 147 all profiles equally, both progressive (e.g., horizonation, clay accumulation, reddening, etc.) and
 148 regressive (e.g., haplodization, erosion, pedoturbation, etc.) pedogenic processes (Johnson and
 149 Watson-Stegner, 1987; Phillips, 1993a), are implicitly captured in the model structure. The
 150 model makes no assumptions about the initial soil forming system; the model simply describes
 151 the probability of a location exhibiting a range of soil properties based on TPE. The model
 152 assumes all changes in soil physical properties are due to pedogenic processes. We used a
 153 bivariate normal distribution; consequently the model assumes the data conforms to a normal
 154 distribution.

155

156 **2. Methods**

157 **2.1 Data collection and preparation**

158 The probability distributions were parameterized using an extensive literature review of
 159 chronosequence studies. Over 140 chronosequence publications were identified using Google
 160 Scholar (scholar.google.com) and ThomsonReuters Web of Science (webofknowledge.com),
 161 forty-five of which contained the data required for inclusion within the present study. Inclusion
 162 within the present study required: profile descriptions with horizon-level clay, sand, and silt
 163 content, soil depth; well-defined ages of the soil-geomorphic surfaces; and geographic
 164 coordinates or maps showing locations of the described profiles. The chronosequences spanned a
 165 wide range of geographic locations, ecosystems, climates, rock types, and geomorphic landforms
 166 (Fig 1, Table S1).



167

168 **2.2 Total Pedogenic Energy**

169 The influence of both climate and vegetation at the locations of each soil profile was
 170 determined using effective energy and mass transfer (EEMT) (Rasmussen and Tabor, 2007;
 171 Rasmussen et al., 2005). The EEMT values for each soil profile were extracted from a global
 172 map of EEMT derived from the monthly global climate dataset of New et al. (1999) at 0.5°x0.5°
 173 resolution using ArcMap 10.1 (ESRI, Redlands, CA) (Rasmussen et al., 2011). Total pedogenic
 174 energy (TPE, J m⁻²) was derived simply by multiplying EEMT (J m⁻² yr⁻¹) for each soil profile by
 175 its reported age (yr). TPE was used because it was a better predictor of soil physical properties
 176 relative to mean annual temperature, mean annual precipitation, or net primary productivity
 177 (Table 3).

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179 **2.3 Application to chronosequence data**

180 The chronosequence database included 45 distinct chronosequences representing 416
 181 different soil profiles. We focused here on changes in sand, silt, and clay content and solum
 182 thickness as proxies for soil change with time. We tested the approach on depth weighted (DWT)
 183 sand, silt and clay content (reported as weight %), as well as the maximum measured value of
 184 sand, silt, and clay content within each soil profile. Buried horizons were removed from the soil
 185 profiles before either the maximum or DWT content values were calculated. For soils reported in
 186 McFadden et al. (1986), surficial modern-aged eolian horizons were removed; the reported ages
 187 of the soil-geomorphic surface more closely matched the buried horizons under the eolian
 188 horizons. Solum thickness was extracted for each profile, defined as the thickness of the horizons
 189 influenced by pedogenic processes or the depth to C horizons (Schaetzl and Anderson, 2005).



190 The site RW-14 from McFadden and Weldon (1987) was not included in the solum thickness
 191 model calculations, the measured solum thickness of RW-14 was 1460 cm, an order of
 192 magnitude greater than all other soil profiles included in the study. Four hundred and sixteen
 193 profiles reported clay content data, only 398 profiles reported sand and silt content, and 410 soil
 194 profiles contained a developed solum. We classified the soil profiles by parent material in terms
 195 of igneous, metamorphic, or sedimentary and by geomorphic landform (e.g., alluvial surface,
 196 marine terrace, or moraine, etc.) (Shoeneberger et al., 2012); for example, if a soil was formed on
 197 an alluvial fan from granitic parent material, it would be defined as alluvial and igneous.

198 Using the soils data, we calculated bivariate normal probability distributions using TPE
 199 and the soil physical properties (Eq. 6). The soil data were transformed using logarithmic and
 200 square root transformations when appropriate to meet the normality assumption of the bivariate
 201 normal probability distribution. Conditional univariate normal distributions (Eqs. 7, 8) were
 202 calculated to approximate probable ranges of soil properties using leave one out cross validation
 203 (LOOCV). Each of the soil chronosequences was removed from the model dataset, with the
 204 remaining chronosequence data used to calculate the parameters of the bivariate and conditional
 205 univariate normal distributions. The conditional univariate normal distributions were calculated
 206 using the TPE values for the profiles within the left-out chronosequence.

207

208 **2.4 Application to complex terrain**

209 By design, soil chronosequences are generally sited on gentle, low sloping terrain to
 210 minimize the influence of topography and erosion/deposition on soil formation (Harden, 1982).
 211 However, much of the Earth's surface is characterized by complex topography with high relief,
 212 steep slopes, and differences in slope aspect. Any predictive soil model or approach must be



213 effective in both simple terrain and complex terrain. To test the ability of the model to predict
 214 soil properties in complex terrain, we compiled data from upland catchments with variable parent
 215 material and topography from the literature, as well as data available from the US NSF Critical
 216 Zone Observatory Network (CZO, www.criticalzone.org) (Table 1) (Bacon et al., 2012;
 217 Dethier et al., 2012; Foster et al., 2015; Holleran et al., 2015; Lybrand and Rasmussen, 2015;
 218 Rasmussen, 2008; West et al., 2013). Data from several additional studies from complex terrain
 219 were also included to test the model (Table 1) (Dixon et al., 2009; Yoo et al., 2007). These data
 220 were accessed from: www.criticalzone.org, or Google Scholar (scholar.google.com). These
 221 studies were included because they all contained horizon-level soil texture data, soil depth,
 222 percent volume rock fragment data, and ^{10}Be or U-series measures of soil erosion rates or
 223 residence time, where mean residence time (MRT) was calculated as: $\text{MRT} = h/E$, where h is soil
 224 depth (m) and E is erosion rate (m/yr) (Pelletier and Rasmussen, 2009b). We used published
 225 coordinates to extract EEMT values, calculated from New et al. (1999), for each soil profile
 226 using ArcGIS 10.1, and used EEMT and MRT to calculate TPE. It should be noted the coarse
 227 resolution of New et al. (1999) EEMT values do not account for local scale variation in water
 228 redistribution and primary productivity that can lead to significant topographic variation in
 229 EEMT (Rasmussen et al., 2015). Using Eq. 6 and the parameters generated from the
 230 chronosequence database, conditional mean depth weighted clay content was calculated for each
 231 profile.

232 Due to the influence of redistributive hillslope processes on soil development (Yoo et al.,
 233 2007), soil depth varies systematically across hillslopes (Heimsath et al., 1997); thus, soil depth
 234 can be used to incorporate information about these processes within the model calculations. We



calculated the mass per area clay content of these profiles using soil depth to correct for these processes, as:

$$\text{Mass per area clay (kg m}^{-2}\text{)} = (\rho_b)(h) \left(\frac{\mu_{Y|X=x, \text{DWT CLAY}}}{100} \right) \left(1 - \left(\frac{\text{RF}\%}{100} \right) \right) \quad (9)$$

where, ρ_b is the soil bulk density assumed to be 1500 kg m^{-3} for all soil profiles, $\mu_{Y|X=x, \text{DWT CLAY}}$ is the predicted conditional mean for depth weighted clay content (DWT CLAY) using Eq. 7, RF% is the measured depth weighted percent volume rock fragments within the soil, when no RF% data were available we assumed a value of 41.7%, which was the average RF% for profiles with reported values, and h is the soil depth in meters. Using Eq. 9, mass per area clay was calculated for each soil profile. Further, we examined the impact of depth, rock fragment percentage, and predicted conditional mean DWT clay on the predicted mass per area clay predictions using multiple linear regression.

2.4.1 Coupling geomorphic model with probabilistic model

Additionally, we applied the model independent of measured soil data, across a small complex catchment in the Santa Catalina Mountains (Catalina-Jemez CZO, Fig 2a-b, Table 1) (Holleran et al., 2015; Lybrand and Rasmussen, 2015). The ~6 ha catchment is located at an elevation between 2300-2500 m with mixed conifer vegetation, approximately 30 km northeast of Tucson, AZ (Fig 2, Table 1). The approach utilized soil depth and residence time output from a process-based numerical soil depth model. The model used high resolution LiDAR derived topographic data to estimate 2 m pixel resolution soil depth and erosion rates (Fig 2c) (Pelletier and Rasmussen, 2009a). These data were coupled with topographically resolved EEMT values that accounted for local hillslope scale variation in water redistribution and primary productivity at a 10 m pixel resolution (Rasmussen et al., 2015) (Fig 2d). We used TPE based on modeled



EEMT and soil residence time to predict DWT clay, and coupled with modeled depth in Eq. 9 to predict mass per area clay at 2 m pixel resolution. We assumed a constant 50% rock fragment value for each location. The coupled geomorphic-TPE model outputs were compared with point measures of mass per area clay from Holleran et al. (2015) and Lybrand and Rasmussen (2015). Model data were completely independent from Holleran et al. and Lybrand and Rasmussen and these datasets served as a validation for the modeled output.

3. Results

3.1 Application and parameterization to chronosequences

The relationships between TPE and soil texture and solum thickness were used to calculate the bivariate probability distributions. The bivariate probability distributions (Eq. 6) were parameterized using the chronosequence database (Table 2). Furthermore, the relationship between TPE and the soil properties was stronger than just using age, NPP, MAP, or MAT alone (Table 3). Age was expected to strongly correlate to the soil properties due to the design of chronosequence studies; however, comparing age and TPE separately, the percent increase in Spearman rank correlations (r) ranged from 1.9% (DWT Silt) to 22.4% (Max Sand). Maximum and depth weighted silt content were weakly correlated to both age and TPE and exhibited only a minimal change in Spearman's rank correlation with TPE relative to age.

The correlation between TPE and maximum clay content (Fig 3, $\rho=0.78$, $r^2=0.61$, $\sqrt{\text{Max Clay}} = -7.35 + 1.36 * \log(\text{TPE})$, $df=414$) was highly significant, and presented the strongest probabilistic relationship determined between TPE and the soil properties. The bivariate probability surface displayed the greatest probability around the joint means between TPE and maximum clay content (Fig 3). Solum thickness and TPE were also strongly related,



281 but weaker relative to the maximum clay-TPE relationship (Fig S1, $\rho=0.65$, $r^2=0.42$,
 282 $\log(\text{solum thickness}) = -0.57 + 0.27 * \log(\text{TPE})$, $df=408$). The relationships between TPE
 283 and max sand (Fig S2) and silt (Fig S3) contents were generally weaker, relative to clay and
 284 solum thickness, with little to no relationship between TPE and silt content.

285 The conditional univariate normal distribution parameters were determined for the soil
 286 physical properties from the bivariate distribution and using Eqs. 7 and 8. The bivariate normal
 287 distribution effectively predicted maximum clay content (Fig 4) with an $r^2 = 0.54$
 288 (RMSE=14.7%) between the measured maximum clay content and predicted conditional mean
 289 maximum clay content (Eq. 7) across all sites based on LOOCV (Fig 4d). The model effectively
 290 predicted maximum clay content for each parent material with r^2 of 0.60 (RMSE=14.1%), 0.56
 291 (RMSE=11.9%), and 0.59 (RMSE=16.7%), for igneous, metamorphic, and sedimentary parent
 292 materials, respectively. The r^2 between the measured values and predicted values for solum
 293 thickness, max sand, and max silt were 0.28 (RMSE=99.8 cm, Fig S4), 0.17 (RMSE=23.2%, Fig
 294 S5), and 0.04 (RMSE=18.0%, Fig S6), respectively.

295 The relationship of predicted to actual maximum clay content varied significantly across
 296 individual studies. The predicted values represent the predicted conditional means (Eq. 7)
 297 bounded by the conditional standard deviation (Eq. 8), which approximates a 50% probability
 298 that the measured maximum clay content will be within 1 standard deviation of the conditional
 299 mean (Fig 5). The individual studies presented in Fig 5 were selected to represent a broad range
 300 of climates and landforms, and demonstrate both the strengths and weaknesses of the model. For
 301 Harden (1987) (Fig 5a, $r^2=0.88$, $p<0.0001$, $df=20$, RMSE=9.3%) and Howard et al. (1993) (Fig
 302 5b, $r^2=0.86$, $p<0.001$, $df=6$, RMSE=9.8%), the model was generally successful at predicting the
 303 maximum clay content values; both the Harden (1987) and Howard et al. (1993) sequences were



located in alluvial deposits but in vastly different climates, xeric (winter-dominated annual rainfall regime) vs. udic (evenly distributed annual rainfall regime), respectively. The model was capable of predicting maximum clay content values for glacial moraine deposits, in a frigid climate (Fig 5c, $r^2=0.87$, $p<0.0001$, $df=12$, $RMSE=6.1\%$ Birkeland, 1984) and on marine terraces in Northern California with a xeric climate (Fig 5f, $r^2=0.98$, $p<0.001$, $df=4$, $RMSE=8.7\%$, Merritts et al., 1991). The model was incapable of predicting clay accumulation on marine terraces in hot, wet climates in Barbados (Fig 5d, $r^2=0.31$, $p=0.08$, $df=9$, $RMSE=45.1\%$ Muhs, 2001) or Taiwan (Fig 5e, $r^2=0.67$, $p<0.001$, $df=11$, $RMSE=23.2\%$, Huang et al., 2010).

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3.2 Application in complex terrain

The model was much less effective in complex terrain and highly overpredicted DWT clay contents in soils located in complex landscapes (Fig 6a, $r^2=0.26$, $y=0.39x+7.27$, $p<0.0001$, $RMSE=5.3\%$). The model highly over predicted the clay content of the South Carolina site and the Gordon Gulch soils, and under predicted the clay content of the Rincon, Santa Catalina, Jemez sites.

When correcting for the influence of hillslope processes by explicitly including soil depth and calculating mass per area clay, the approach effectively predicted clay content, with an $r^2=0.81$ (Fig 6b, $y=1.56x-15.2$, $p<0.0001$, $RMSE=84.4 \text{ kg clay m}^{-2}$), only slightly overpredicting clay content, with a slope of 1.56. Soil depth was the strongest contributing factor to the mass per area clay prediction with the greatest sums of squares in a simple multiple linear regression including depth, RF%, and DWT clay% (Table 4); predicted conditional mean clay content percentage was the second strongest contributing factor to the mass per area clay prediction. Rock fragment percentage did not influence the mass per area clay content prediction.



327

328 **3.3 Coupled geomorphic-TPE model**

329 The coupled geomorphic-TPE model effectively predicted mass per area clay for the
 330 majority of soils located within the Marshall Gulch subcatchment with an $r^2=0.74$ (Fig 7a,
 331 $y=0.85x-5.00$, $p<0.0001$, $RMSE=17.7 \text{ kg clay m}^{-2}$). For a subset of soils, the model did not
 332 effectively predict mass per area clay, and were excluded from the regression in Fig 7a; four of
 333 these soils were located on the east-facing ridge of the catchment, and an additional two soils
 334 were formed on amphibolite rather than the granite or quartzite materials that all of the other
 335 soils in the catchment were derived from. All of these locations also exhibited a poor fit between
 336 modeled and measured soil depth (Fig 2e). The spatial distribution of mass per area clay was also
 337 predicted across the catchment (Fig 7b), independently of measured data, and generally
 338 conformed to previously predicted spatial distribution of clay stocks in the Marshall Gulch
 339 catchment (Holleran et al., 2015).

340

341 **4. Discussion**

342 **4.1 Model effectiveness**

343 **4.1.1 Model results for chronosequences**

344 The model predicted maximum clay content across a diverse range of lithologies,
 345 climates, and landforms. Weathering and clay production are primary pedogenic processes
 346 (Birkeland, 1999; Schaetzl and Anderson, 2005), and because the model assumed all changes in
 347 the soil profile are due to these processes, the model was the most effective at predicting clay
 348 content. For initial soil states that begin pedogenesis with a potentially significant amount of
 349 clay-sized particles the model was much less effective. The soils of the Taiwanese



350 chronosequence formed from conglomerates (Huang et al., 2010); conglomerates are typically
 351 poorly sorted, such that these soils initially formed with high clay contents slowing clay
 352 accumulation, limiting the effectiveness of the model to predict clay contents in these soils.
 353 Additionally, the model highly underestimated the clay content of soils located on coral reef
 354 terraces in tropical environments (Maejima et al., 2005; Muhs, 2001). Coral reef terraces
 355 represent a relatively unique landform that weathers rapidly to fine sized particles, especially
 356 under tropical climates, and generally have complicated parent material compositions (Muhs et
 357 al., 1987). The combination of these factors limited the ability of the model to predict the soil
 358 properties on these surfaces.

359 Sand and silt displayed weaker relationships with increasing total pedogenic energy. The
 360 lack of correlation of sand and silt to TPE may result in part from the definitions of the particle
 361 size classes. Sand sized particles span several orders of magnitude difference in particle size,
 362 ranging from particles of 2 mm to 0.05 mm (Soil Survey Staff, 2010), whereas clays are
 363 constrained to particles less than 0.002 mm. The sequential weathering of rock fragments and
 364 coarse sand to fine and very fine sands therefore is not reflected in total sand content and likely
 365 diminishes the relationship between sand content and total pedogenic energy and time (Pye and
 366 Sperling, 1983; Pye, 1983; Sharmeen and Willgoose, 2006). The relationship between silt
 367 content and pedogenic energy was the weakest of the three broad particles size classes (Tables 2,
 368 3). Similar to sand, the silt size fractions span an order of magnitude in particle size ranging from
 369 0.05 to 0.002 mm in diameter. Additionally, the silt fraction may also be heavily influenced by
 370 deposition of eolian material and thereby introduce an additional mass of silt that was not
 371 derived from the direct weathering of the initial soil forming system (McFadden et al., 1987)
 372 effectively uncoupling silt content from total pedogenic energy.



373 Solum thickness displayed a relatively strong relationship with increasing pedogenic
374 energy, with TPE explaining up to 42% of the variance in solum thickness (Tables 2, 3). Soil
375 production is related to climatic variation (Amundson et al., 2015), with this variation partly
376 captured by EEMT and TPE, leading to the slightly stronger predictive power of the model.
377 However, soil production is also highly influenced by redistributive hillslope process, chemical
378 and physical weathering, and tectonic uplift (Heimsath et al., 1997; Riebe et al., 2004; Yoo and
379 Mudd, 2008b), and can be a highly non-linear process (Pelletier and Rasmussen, 2009a). These
380 factors were not directly accounted for in this study in that topography was not a quantified
381 factor, which likely represents a large proportion of the remaining unexplained variance in solum
382 thickness.

383

384 **4.1.2 Model results in complex terrain**

385 Due to using soil chronosequence data to parameterize the approach, the influence of
386 redistributive hillslope processes was not captured. Additionally, in the amount of time required
387 to transport soil across a hillslope, chemical and physical alterations of the soil particles are
388 possible and may not be reflected in mean residence time calculations (Yoo and Mudd, 2008a;
389 Yoo et al., 2007). Soil thickness is highly dependent upon hillslope position and landscape
390 morphology (Dietrich et al., 2003; Heimsath et al., 1997; Pelletier and Rasmussen, 2009a). By
391 using soil thickness as a proxy for the strength of these redistributive hillslope processes, and
392 converting the predicted conditional mean clay content value to a mass per area basis, the model
393 was able to capture differences in clay content across complex terrain for a variety of lithologies
394 and climates. The differing lithologies, climates, or vegetation types did not appear to impact the
395 ability of the model to predict clay contents, likely because soil depth accounts for many of these



controls. Parent material and climate influence the weathering process and production of clay in soils (Harden and Taylor, 1983; Muhs et al., 2001); however, these factors are collinear with soil depth (Heckman and Rasmussen, 2011; Lybrand and Rasmussen, 2015; Pelletier and Rasmussen, 2009a), such that by including soil depth, differences due to lithology or climate were partly incorporated in the model prediction.

401

4.1.3 Results from coupled geomorphic-TPE model

For the majority of sites in the Marshall Gulch sub-catchment, the coupled geomorphic-TPE model was highly effective at predicting clay content, and the spatial distribution of clay stocks. Large differences were found for four soils located on the east-facing ridge of the catchment underlain by granite with the model generally over-predicting soil depth and clay content. Discrepancies between the modeled and measured depths were likely the primary sources of error within the mass per area clay predictions for the 4 east-facing ridge soils (Fig 2e). The geomorphic model predicted deeper soil depths due to the presence of an apparent convergent zone on the east-facing ridge of the sub-catchment; however, this convergent zone is only a small feeder tributary to the larger catchment drainage. The inability of the model to effectively predict clay contents and the mismatch between modeled and actual soil depths in the 4 soils located on the east-facing ridge is likely due to this local, fine-scale topographic variation

Error in predicted soil depths due to fine-scale differences in lithology within the Marshall Gulch sub-catchment partly explains the discrepancies between measured and predicted mass per area clay contents. For two amphibolite-derived soils, the model greatly underestimated mass per area clay. The geomorphic soil depth model assumed a uniform weathering rate based on the granitic soils (Pelletier and Rasmussen, 2009a); due to differences in primary mineral



419 assemblage, the amphibolite materials are likely weather at a faster rate compared to the granite
420 derived soils (White et al., 2001; Wilson, 2004), resulting in greater clay production and likely
421 explaining the underestimated clay contents. Inclusion of differential weathering rates for
422 varying lithologies within the geomorphic model would likely lead to better prediction of clay
423 contents. With these adjustments, the coupled geomorphic-TPE model represents an effective,
424 independent prediction of clay stocks.

425

426 **4.2 Advantages of probabilistic approach**

427 Simplifying and representing the soil-forming factors as multivariate distributions and
428 probabilities has the potential to quantitatively represent the general state-factor model, making
429 the approach universally applicable. The initial state of the soil can likely never be fully known,
430 leading to variability in soil properties over time that cannot necessarily, or ever, be attributed to
431 any external factor (Phillips, 1989, 1993b). A probabilistic approach utilizes that variability to
432 drive predictions and understanding of these systems. Similar to the approach taken here,
433 building distributions of the soil-forming state factors that are associated with distributions of
434 particular soil properties could yield probabilistic predictions of soil formation and change. We
435 selected to use a representation of climate and biology (EEMT), however, depending on the soil
436 property of interest the variables needed to parameterize the distributions would likely change;
437 for example, if interested in organic matter content, aboveground net primary productivity or
438 normalized difference vegetation index may be better predictors of organic matter accumulation.
439 The strength of this approach lies in the fact that no assumptions are made about the initial
440 conditions of the soil forming system or the specific soil forming processes. Predicting probable
441 distributions of soil physical properties implicitly acknowledges that our understanding of any



442 system is incomplete, but explicitly quantifies uncertainty in predictions and constrains the
 443 potential observable values to a predicted range. Utilizing this approach will require the
 444 necessary data to build distributions that are widely representative and applicable to most
 445 locations (Yaalon, 1975). With wide accessibility to large databases of soil information, such as
 446 the US National Soil Information System (NASIS) and the FAO Harmonized World Soil
 447 Database, access to the required amount and quality of data may be possible. Similar to the
 448 present study, simple bivariate distributions could be solved to calculate conditional distributions
 449 based on the soil-forming state factors, effectively producing quantitative probabilistic
 450 representations of Jenny's original equation (Jenny, 1941).

451 The simplicity of the present approach allows easy integration into pre-existing
 452 geomorphic models of landscape evolution. Past approaches that have combined pedogenic and
 453 landscape evolution models have generally focused on producing hypothetical soil-landscape
 454 relationships that progress forward through time (Minasny and McBratney, 2001; Vanwalleghe
 455 et al., 2013), or have focused on idealized landscapes (Temme and Vanwalleghe, 2015).
 456 However, by combining probabilistic approaches parameterized using known landscapes, and
 457 geomorphically based landscape evolution models, both potential soil-landscape evolution
 458 scenarios can be investigated, as well as predictions of the current state of the soil-landscape. As
 459 was demonstrated in Fig 7B, combining the present approach with geomorphically based soil
 460 depth models generated from DEMs has great potential to predict soil properties across a diverse
 461 range of environments, without needing prior knowledge of the landscape other than topography
 462 and climate.

463

464 **4.3 Limitations and potential refinements**



465 There are obvious limitations within the current model: lack of consideration of parent
466 material influences, topographic variation, or internal soil feedbacks and thresholds, and
467 differences in paleoclimate variation. Parent material control on the relative proportion of
468 weatherable minerals and mineral weathering rates (Jackson et al., 1948) can manifest as vastly
469 different soil morphologies and rates of pedogenesis when controlling for other soil forming
470 factors (Heckman and Rasmussen, 2011; Parsons and Herriman, 1975). The current approach
471 implicitly assumes no information about the initial conditions, only that all clay production is a
472 pedogenic process. Applying this approach to parent materials, where a large fraction of clay-
473 sized particles formed through non-pedogenic processes, is thus limited and may explain why the
474 model was ineffective for some soils. Refining the current approach would require normalization
475 of soil to the particle size distribution of the soil parent material. Past studies have utilized highly
476 characterized parent material data to model soil property change with time (Chadwick et al.,
477 1990; Harden, 1982), but these data are generally difficult to obtain and often not reported in the
478 available chronosequence literature.

479 Topography dictates soil chemical and physical properties and residence times, especially
480 in complex terrain (Almond et al., 2007; Egli et al., 2008; Lybrand and Rasmussen, 2015), where
481 non-linear diffusive hillslope processes control the fluxes of matter and energy into and out of
482 the soil system (Heimsath et al., 1997; Pelletier and Rasmussen, 2009a; Rasmussen et al., 2015;
483 Yoo and Mudd, 2008b; Yoo et al., 2007). Using earlier versions of EEMT (Rasmussen and
484 Tabor, 2007; Rasmussen et al., 2005), the current formulation of the model and TPE does not
485 explicitly quantify topographic variation, which may account for error within current soil
486 property distributions and predictions. With the inclusion of topographic variation within EEMT
487 (Rasmussen et al., 2015) and topographic control of soil residence times (Foster et al., 2015;



488 West et al., 2013), we were able to correct this error within the present approach, particularly in
489 complex terrain, and effectively predicted clay stocks.

490 Internal or intrinsic feedbacks and thresholds within the soil system drive pedogenic
491 development without changes in the external state factors (Chadwick and Chorover, 2001; Muhs,
492 1984). For example, greater chemical weathering and clay production due to increased water
493 residence time caused by argillic horizon development is the result of an internal feedback that is
494 independent of the external climatic and biological system (Schaetzl and Anderson, 2005). These
495 thresholds can operate as progressive or regressive processes, driving soil formation forward or
496 hindering further development (Johnson and Watson-Stegner, 1987; Phillips, 1993a). Internal
497 soil development feedbacks were not explicitly considered in the present model formulation. The
498 presence of these internal feedbacks may partially explain error within the model predictions.
499 Changes in EEMT would not explain all observed differences in soil properties over the age of
500 the soil. However, if these feedbacks were operating in the included soils, the influence of
501 intrinsic thresholds was implicitly captured within the probability distributions, partially
502 accounting for the role of internal soil development feedbacks on soil formation.

503 Furthermore, global climate patterns have shifted dramatically over the last 65 Mya
504 (Zachos et al., 2001). The majority of soils observed in the compiled chronosequence database
505 span the Quaternary, including both the Holocene and Pleistocene. The Pleistocene was marked
506 by a number of major glacial-interglacial cycles at approximately 100,000-year intervals (Imbrie
507 et al., 1992; Wallace and Hobbs, 2006), which corresponded with shifting climatic conditions,
508 e.g., for large portions of the northern mid-latitudes glacial periods were generally cooler and
509 wetter, and interglacial periods were warmer and drier (Connin et al., 1998; Petit et al., 1999).
510 Further, the Pleistocene climate shifts likely influenced the rates of weathering and clay



511 production (Hotchkiss et al., 2000). Taking into account the differences in past and modern
512 climate would likely diminish disparities between observed and modeled soil physical properties.
513 Reconstructed global paleo-EEMT values would improve model accuracy, and limit uncertainty
514 in the probabilistic ranges of soil properties for soils older than Holocene age.

515

516 **5. Conclusion**

517 The present approach effectively predicts soil physical properties across a diverse range
518 of geomorphic surfaces, lithologies, ecosystems, and climates. Further, this approach is
519 mathematically simple and only requires knowledge of the probable age of a geomorphic surface
520 and the effective energy and mass transfer value associated with a given location, making this
521 approach universally applicable. The simplicity of the probabilistic approach is the lack of
522 assumptions about the initial conditions of the soil forming state or the processes driving soil
523 property change. A probabilistic approach does not exactly predict a soil physical property value
524 at a given location, but constrains the probable values based upon the state of the external
525 environment to the soil. Using probabilistic approaches, we can model probable soil-landscape
526 evolution scenarios, greatly informing our understanding of the evolution of critical zone
527 structure.

528

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List of Figures and Tables

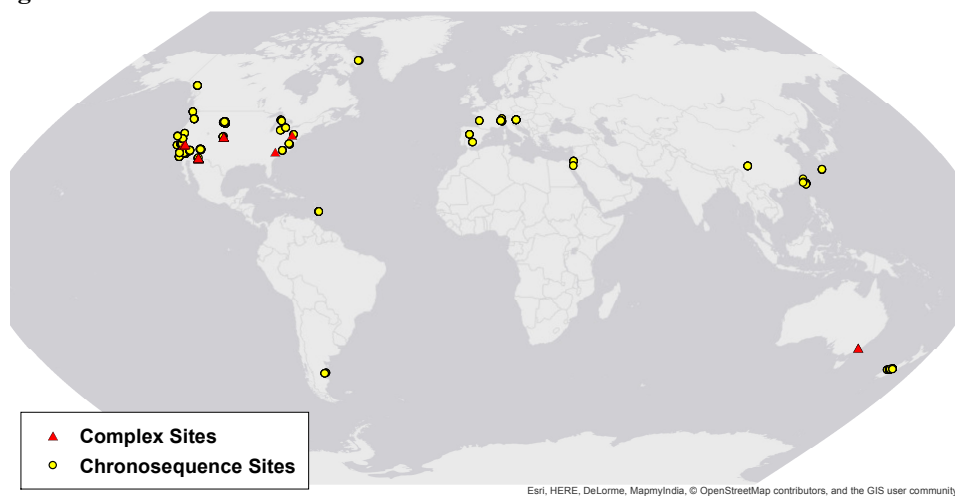


Figure 1. Map of study sites. Yellow points indicate location of chronosequences, and red triangles indicate location of soils in complex terrain.



Table 1. Complex terrain study sites and characteristics.

Site	Study	Number of Sites	Elevation (m)	MAP (cm)	MAT (°C)	Parent Material	Slope	Aspect	Vegetation
Marshall Gulch Granite Subcatchment, Arizona, USA	Holleran et al., 2015. <i>SOIL</i> . 1:47-64. Lybrand and Rasmussen. 2015. <i>SSSAJ</i> . 79, 1: 104-116	24	2300-2500	85-90	10	Granite, Amphibolite, Quartzite	45%	North	<i>Pinus ponderosa</i> , <i>Pseudotsuga menziesii</i> , <i>Abies concolor</i>
Frog's Hollow, New South Wales, Australia	Yoo et al., 2007. <i>JGR</i> . 112: F02013	2	930	55-75	~16	Granodiorite	-	-	<i>Eucalyptus</i> grassland savannah
Cross Keys, South Carolina, USA	Bacon et al., 2012. <i>Geology</i> . 40, 9: 847-850	1	-	115-140	14-18	Granitic gneiss	<2%	-	<i>Quercus</i> , <i>Carya</i>
Gordon Gulch, Colorado, USA	Foster et al., 2015. <i>GSA Bulletin</i> . 127, 5/6: 862-878; Dethier et al., 2012. <i>Geomorph</i> . 173-174: 17-29	9	2440-2740	52	5	Gneiss, Quartz monzonite, granodiorite	15° - 28°	North and South	<i>Pinus ponderosa</i> , <i>Pinus contorta</i>
Rincon Mountains, Arizona, USA	Rasmussen, 2008. <i>Geochem. Cosmochim. Acta</i> . 72: A778.	11	1050-2500	<40-80	10-18	Granodiorite(?)	-	-	Oak grass woodland, Piñon-Juniper woodland, Mixed Conifer
Jemez Mountains, New Mexico, USA	Huckle et al., 2016. <i>Chem. Geol.</i> in press.	4	2990-3100	~50	4	Rhyolite, tuff	-	West and East	<i>Pseudotsuga menziesii</i> , <i>Abies concolor</i> , <i>Picea pungens</i> , <i>Populus tremuloides</i>
Shale Hills, Pennsylvania, USA	West et al., 2013. <i>JGR: Earth Surf.</i> 118: 1877-1896; Ma et al., unpublished	6	260-280	100	-	Shale, sandstone	15° - 20°	North and South	-
Sierra Nevada Mountains, California, USA	Dixon et al., 2009. <i>Earth Surf. Proc. Landf.</i> 34: 1507-1521	5	216-2991	37-106	3.9-16.6	Tonalite, granodiorite	-	-	Oak-grass woodland, Mixed Conifer, Subalpine

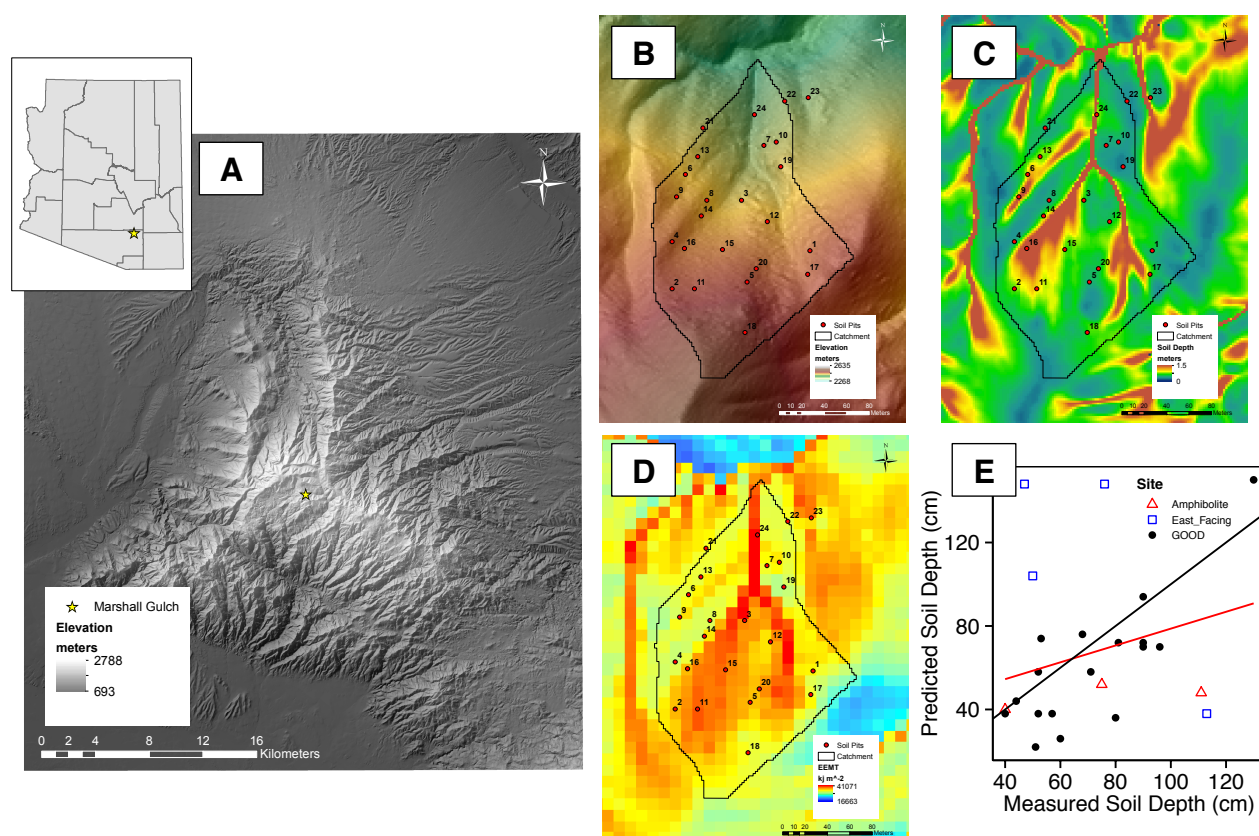


Figure 2. Marshall Gulch study site. (A) Location of the Santa Catalina Mountains and the Marshall Gulch catchment within Arizona, USA; (B) Elevation of the granite sub-catchment of Marshall Gulch; (C) Predicted soil depth in the granite sub-catchment (Pelletier and Rasmussen, 2009a); (D) EEMTv2.0 in the granite sub-catchment (Rasmussen et al., 2015); (E) Mismatch between the measured soil depths and predicted soil depths.



Table 2. Parameters for the bivariate normal probability distributions for the soil physical properties and TPE.

Table 2. Soil property parameters

Variable	n	μ	σ	ρ^a
Max Sand	398	70.51	25.39	-0.48
Max Silt	398	34.80	18.38	0.32
Max Clay ^b	416	4.52	2.24	0.78
DWT Sand	398	59.03	26.04	-0.57
DWT Silt ^b	398	4.55	1.68	0.26
DWT Clay ^b	416	3.66	2.09	0.73
Solum Thickness ^c	410	1.77	0.52	0.65
	416 ^d	8.71	1.29	-
TPE ^c	398 ^e	8.72	1.28	-
	410 ^f	8.73	1.26	-

^a ρ , Pearson correlation between soil variables and Total Pedogenic Energy

^bSquare root transformed

^cLog10 transformed

^dFor clay variables

^eFor sand and silt variables

^fFor solum thickness

n = number of profiles, μ = mean, σ = standard deviation

Max indicates maximum content

DWT indicates depth weighted average content



Table 3. Spearman rank correlations between soil physical properties and TPE and age.

Table 3. Spearman Rank Correlations

Variable	NPP	MAP	MAT	TPE	Age	% Increase ^a	n
Max Sand	-0.30	-0.10	-0.26	-0.46	-0.37	22.4	398
Max Silt	-0.03	-0.16	0.09	0.31	0.32	-4.5	398
Max Clay	0.15	-0.01	0.36	0.80	0.73	9.3	416
DWT Sand	-0.22	-0.04	-0.29	-0.57	-0.50	14.1	398
DWT Silt	0.05	-0.06	0.06	0.24	0.23	1.9	398
DWT Clay	0.21	0.02	0.39	0.75	0.67	12.4	416
Solum Thickness	0.12	0.06	0.22	0.63	0.57	10.4	410

Max indicates maximum content

DWT indicates depth weighted average content

^aPercent increase in Spearman rank correlation between TPE and age

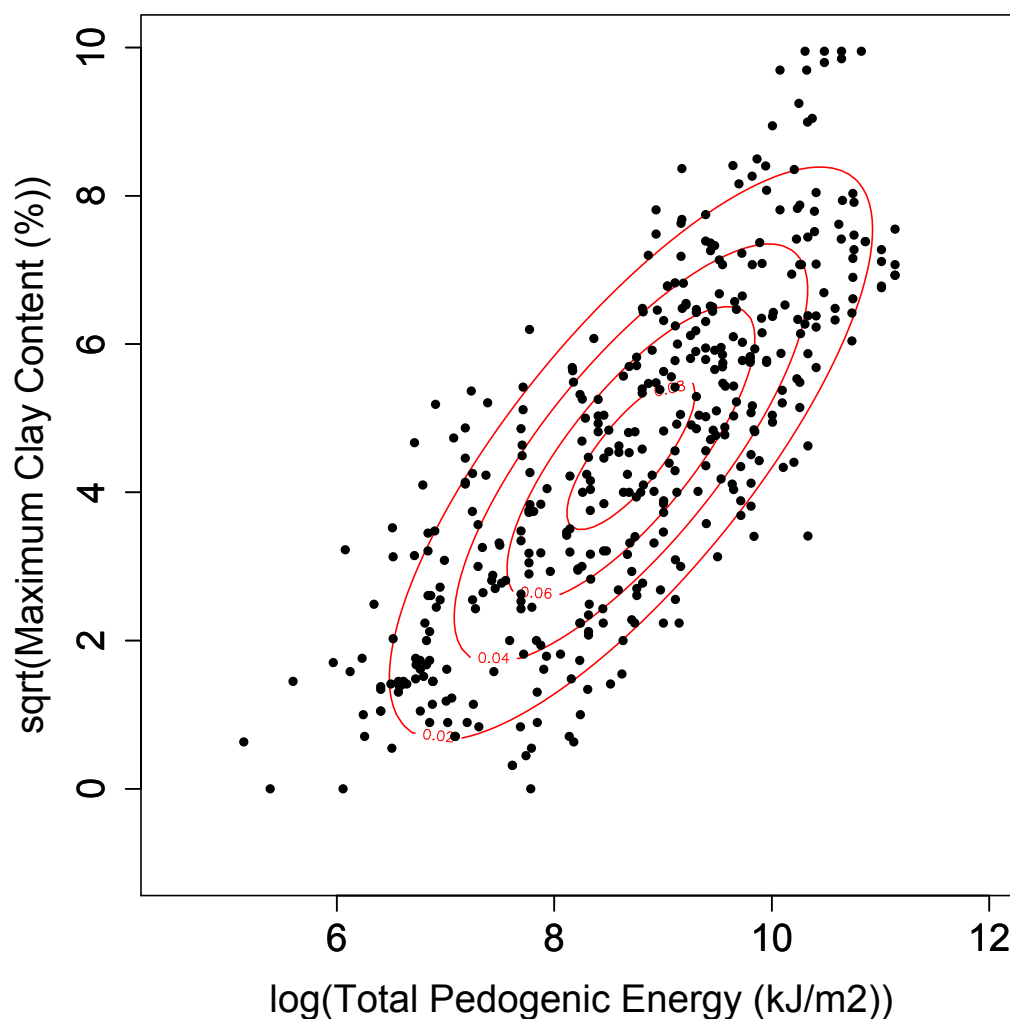


Figure 3. Bivariate normal distribution between TPE and max clay content. The points indicate individual soils. The red ellipses represent lines of equal probability, which corresponds to a three dimensional probability distribution. From this relationship the conditional mean and variances for the soil physical properties were calculated.

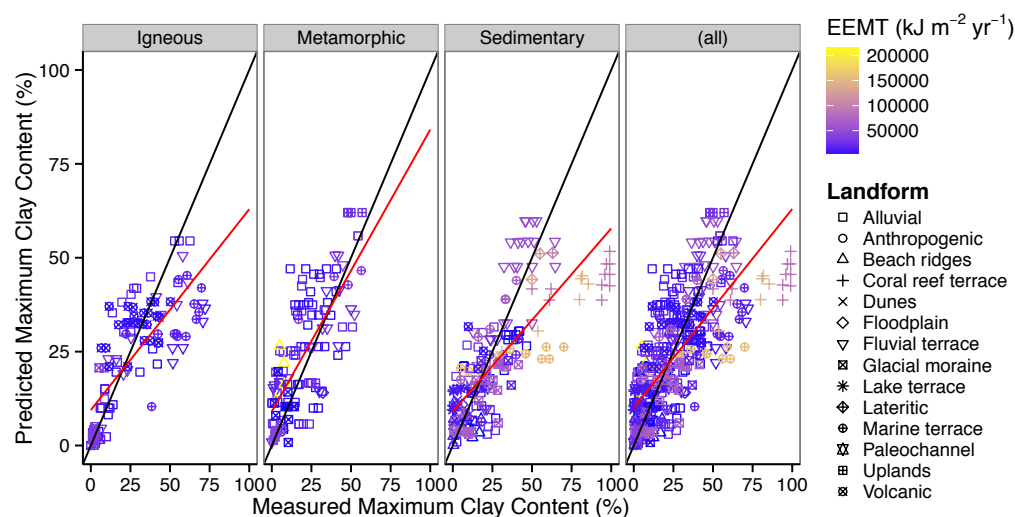


Figure 4. LOOCV results for max clay content. The results were subdivided by general soil parent material: igneous, metamorphic, and sedimentary; the points represent the geomorphic surface each soil formed on, and the colors represents the EEMT value for the location of each soil. Using LOOCV, where one chronosequence was removed from the model dataset and the remaining datasets were used to predict the parameters of the bivariate distributions, the conditional means of the left out chronosequence was determined. The model was effectively able to predict the conditional mean values of the max clay contents with an $r^2=0.54$ (RMSE=14.7%). The model was least capable of predicting the clay contents on coral reef terraces (+), and appeared the most effective for alluvial surfaces (□).

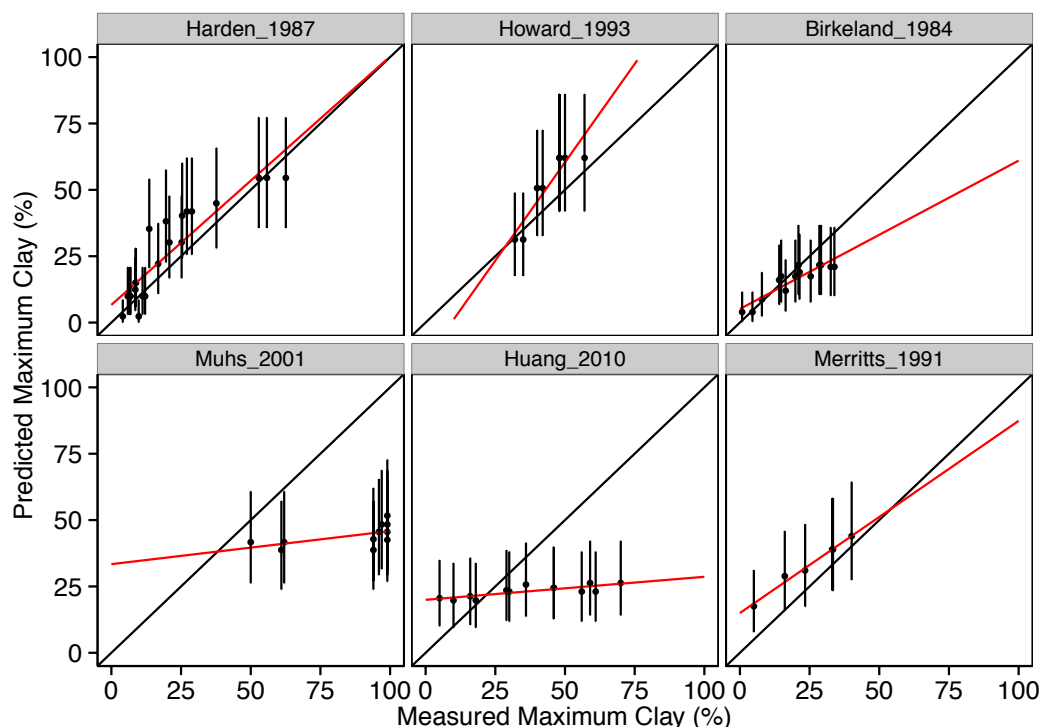


Figure 5. Selected relationships between the measured maximum clay content and predicted maximum clay content. A) Harden, 1987, B) Howard et al., 1993, C) Birkeland 1984, D) Muhs, 2001, E) Huang et al., 2010, and F) Merritts et al., 1991. The errors represent the conditional standard deviations around the mean, which correspond to a probability of 50%. The model effectively predicted clay content across a diverse range of climates, landforms, and parent materials. The model was the least effective at predicting the clay content of soils in tropical climates, and soils forming on coral reef terraces.

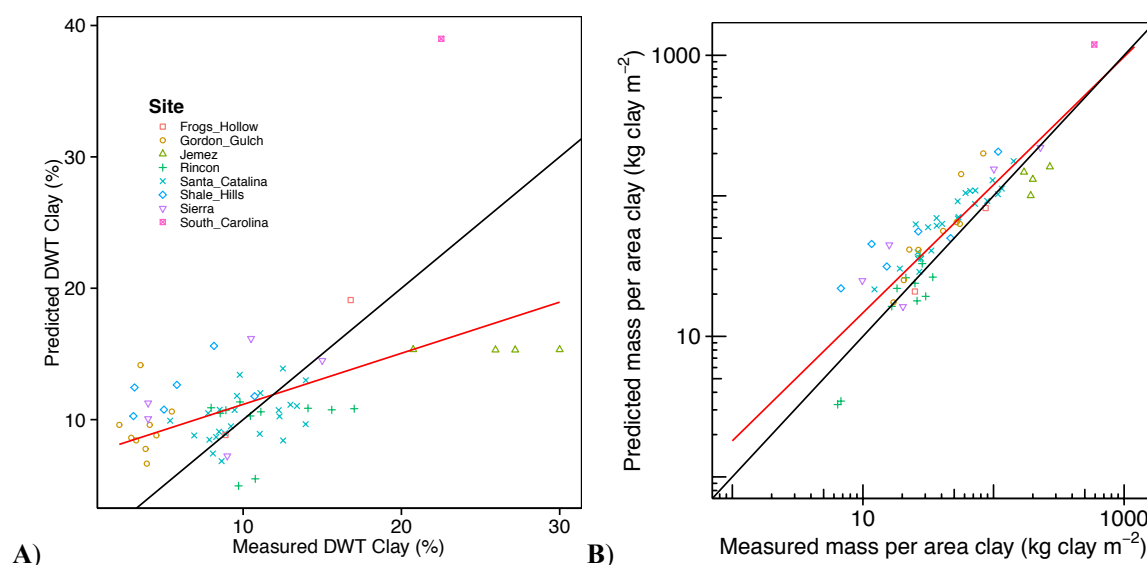


Figure 6. Model results in complex terrain. (A) Prediction of depth weighted (DWT) clay contents; (B) Prediction of mass per area clay using Eq. 9. The model was incapable of directly predicting DWT clay for the soils in complex terrain due to redistributive hillslope processes, $r^2=0.25$ between measured and predicted conditional mean DWT clay (A). By including information about soil depth and percent volume rock fragment, and converting DWT clay to mass per area clay, the model was significantly more effective at predicting clay contents for these soils $r^2=0.81$.



Table 4. Sensitivity analysis of model prediction in complex terrain.

Table 4. Sensitivity analysis of model prediction in complex terrain

Effects	DF	Sums of Squares	Mean Sums of Squares	F value	p
Depth, h (cm)	1	1129156	1129156	469.0	< 2e-16
CM DWT Clay, $\mu_{Y X=x}$ (%)	1	142430	142430	59.2	2.0E-10
Rock fragment, RF% (%)	1	3013	3013	1.3	0.27
Residuals	58	139632	2407		

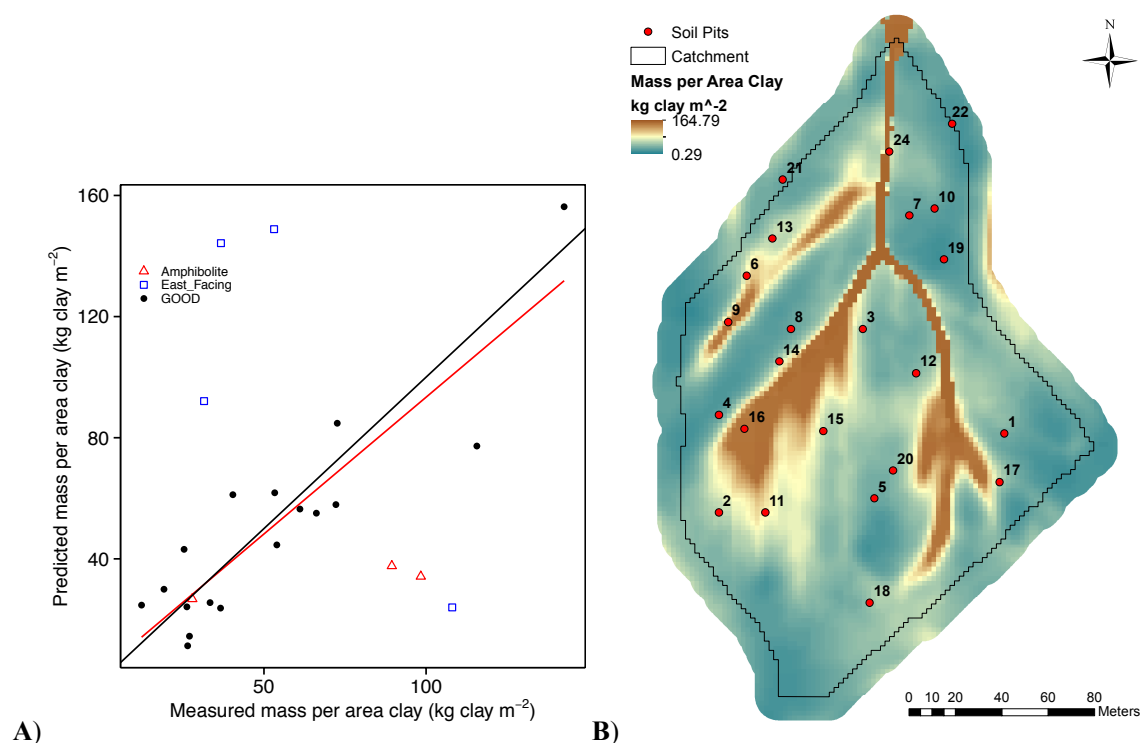


Figure 7. Model results of coupled geomorphic-EEMT-TPE model in Marshall Gulch granite sub-catchment. (A) Prediction of mass per area clay for sites from Holleran et al. (2015) and Lybrand and Rasmussen et al. (2015); (B) Spatial prediction of mass per area clay When combining the present approach, with a geomorphic based soil depth model, the combined models together were highly effective at predicting the clay contents for a majority of soils in the Santa Catalina Mountains (Catalina-Jemez CZO), $r^2=0.74$.